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# HM5112805F-6, HM5113805F-6

128M EDO DRAM (16-Mword × 8-bit)  
8k refresh/4k refresh

## HITACHI

ADE-203-1050C (Z)  
Rev. 3.0  
Feb. 2, 2000

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### Description

The Hitachi HM5112805F, HM5113805F are 128M-bit dynamic RAMs organized as 16,777,216-word × 8-bit. They have realized high performance and low power by employing CMOS process technology. HM5112805F, HM5113805F offer Extended Data Out (EDO) Page Mode as a high speed access mode. They are packaged in 32-pin plastic TSOPII.

### Features

- Single 3.3 V supply: 3.3 V ± 0.3 V
- Access time: 60 ns (max)
- Power dissipation
  - Active: 720 mW (max) (HM5112805F)  
792 mW (max) (HM5113805F)
  - Standby : 3.6 mW (max) (CMOS interface)  
: 1.8 mW (max) (CMOS interface) (L-version)
- EDO page mode capability
- Refresh cycles
  - $\overline{\text{RAS}}$ -only refresh
    - 8192 cycles/64 ms (HM5112805F)
    - 4096 cycles/64 ms (HM5113805F)
  - CBR/Hidden refresh
    - 4096 cycles/64 ms (HM5112805F, HM5113805F)

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## HM5112805F-6, HM5113805F-6

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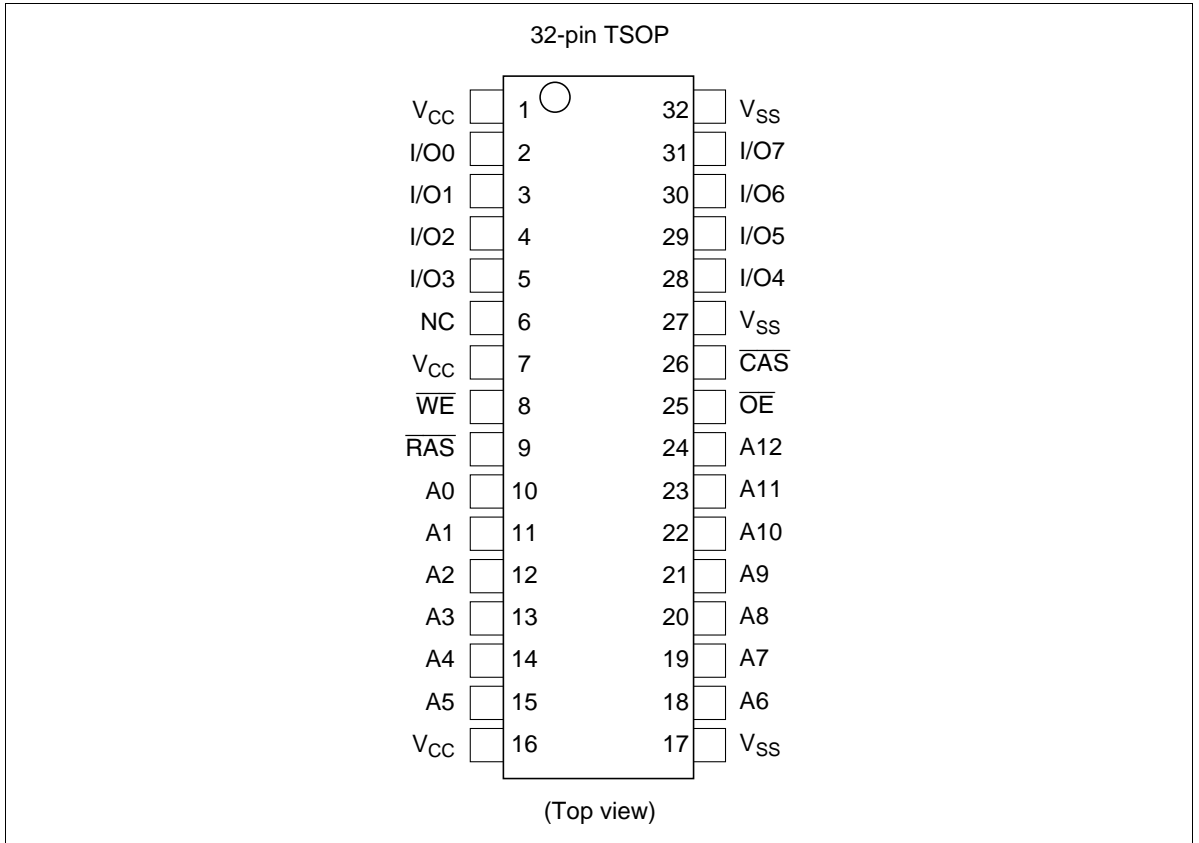
- 4 variations of refresh
  - $\overline{\text{RAS}}$ -only refresh
  - $\overline{\text{CAS}}$ -before- $\overline{\text{RAS}}$  refresh
  - Hidden refresh
  - Self refresh (L-version)
- Battery backup operation (L-version)

### Ordering Information

Type No.	Access time	Package
HM5112805FTD-6	60 ns	400-mil 32-pin plastic TSOP II (TTP-32DF)
HM5112805FLTD-6	60 ns	
HM5113805FTD-6	60 ns	
HM5113805FLTD-6	60 ns	

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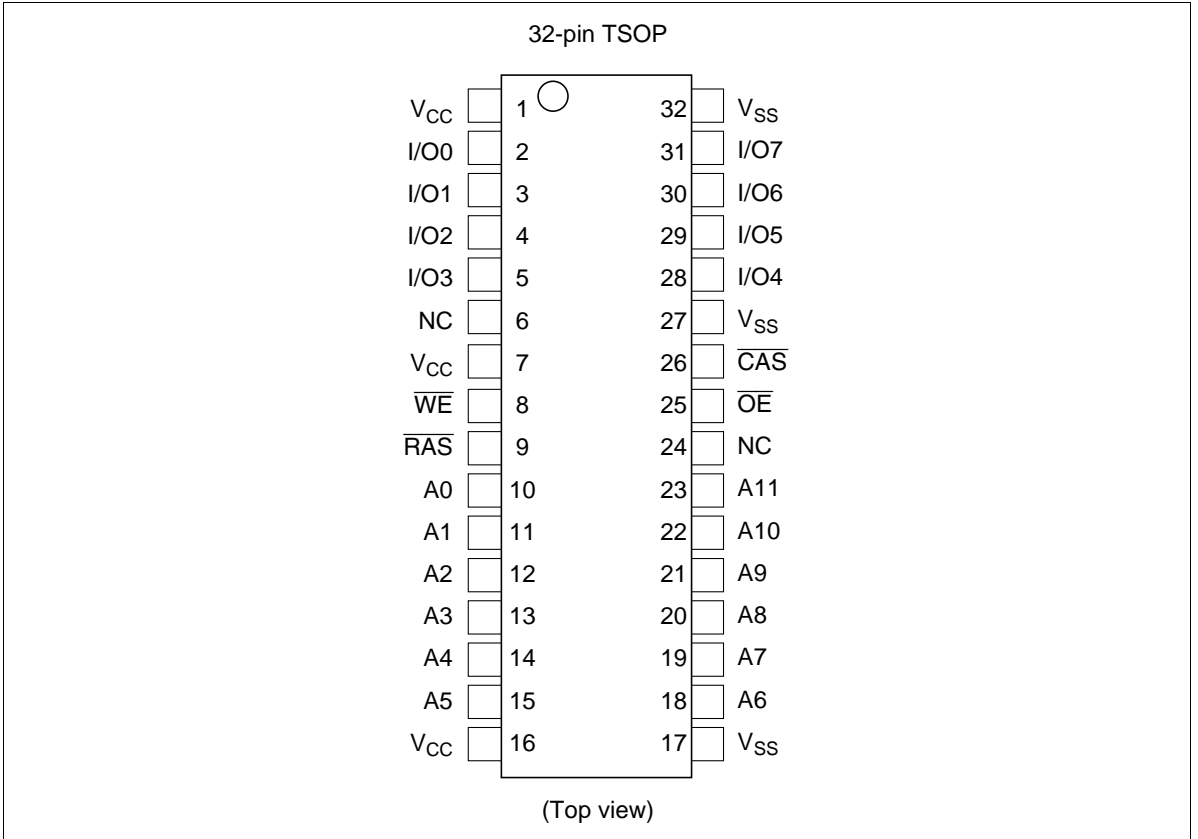
Pin Arrangement (HM5112805F)



Pin Description

Pin name	Function
A0 to A12	Address input — Row/Refresh address A0 to A12 — Column address A0 to A10
I/O0 to I/O7	Data input/output
$\overline{RAS}$	Row address strobe
$\overline{CAS}$	Column address strobe
$\overline{WE}$	Write enable
$\overline{OE}$	Output enable
$V_{CC}$	Power supply
$V_{SS}$	Ground
NC	No connection

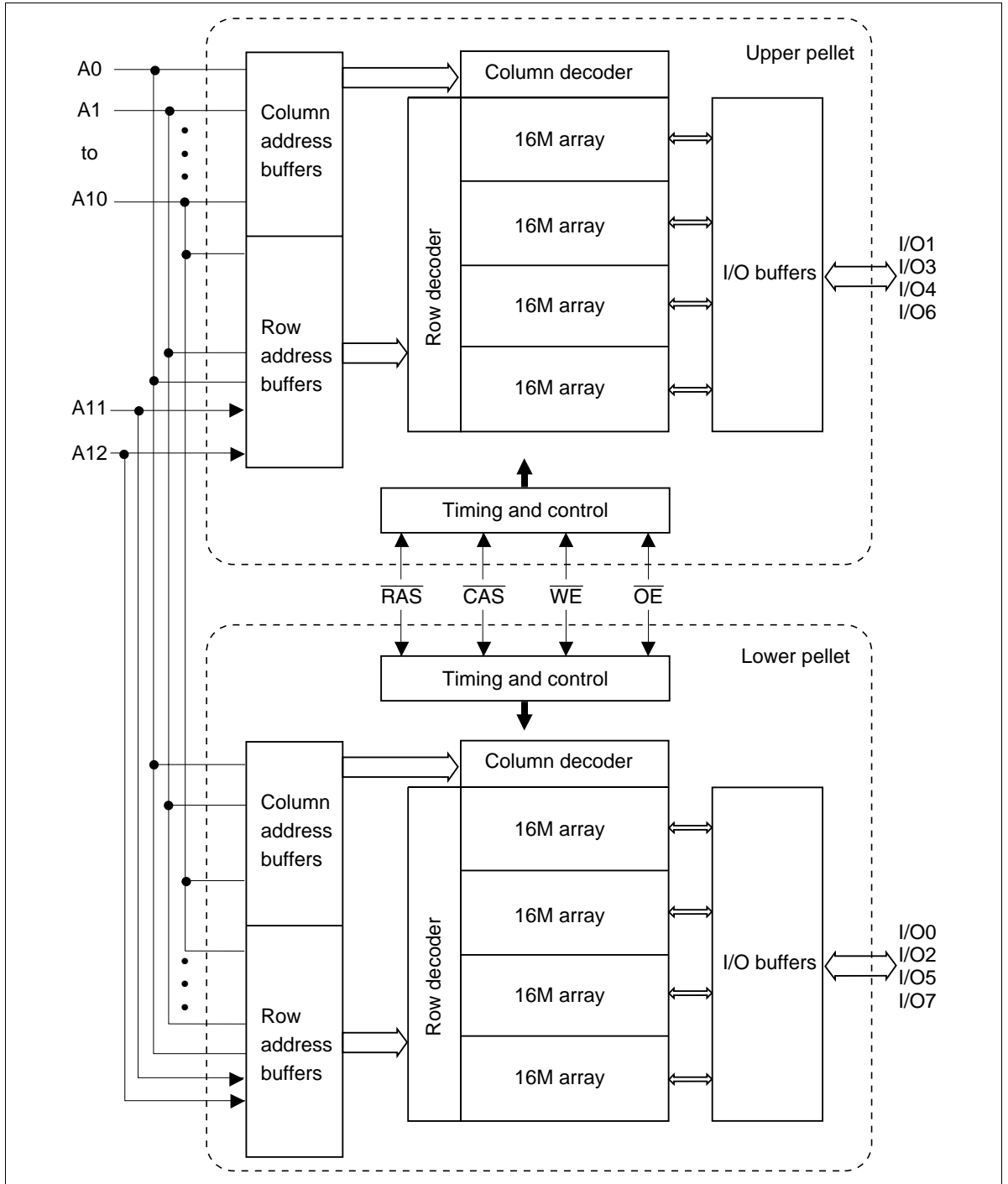
## Pin Arrangement (HM5113805F)



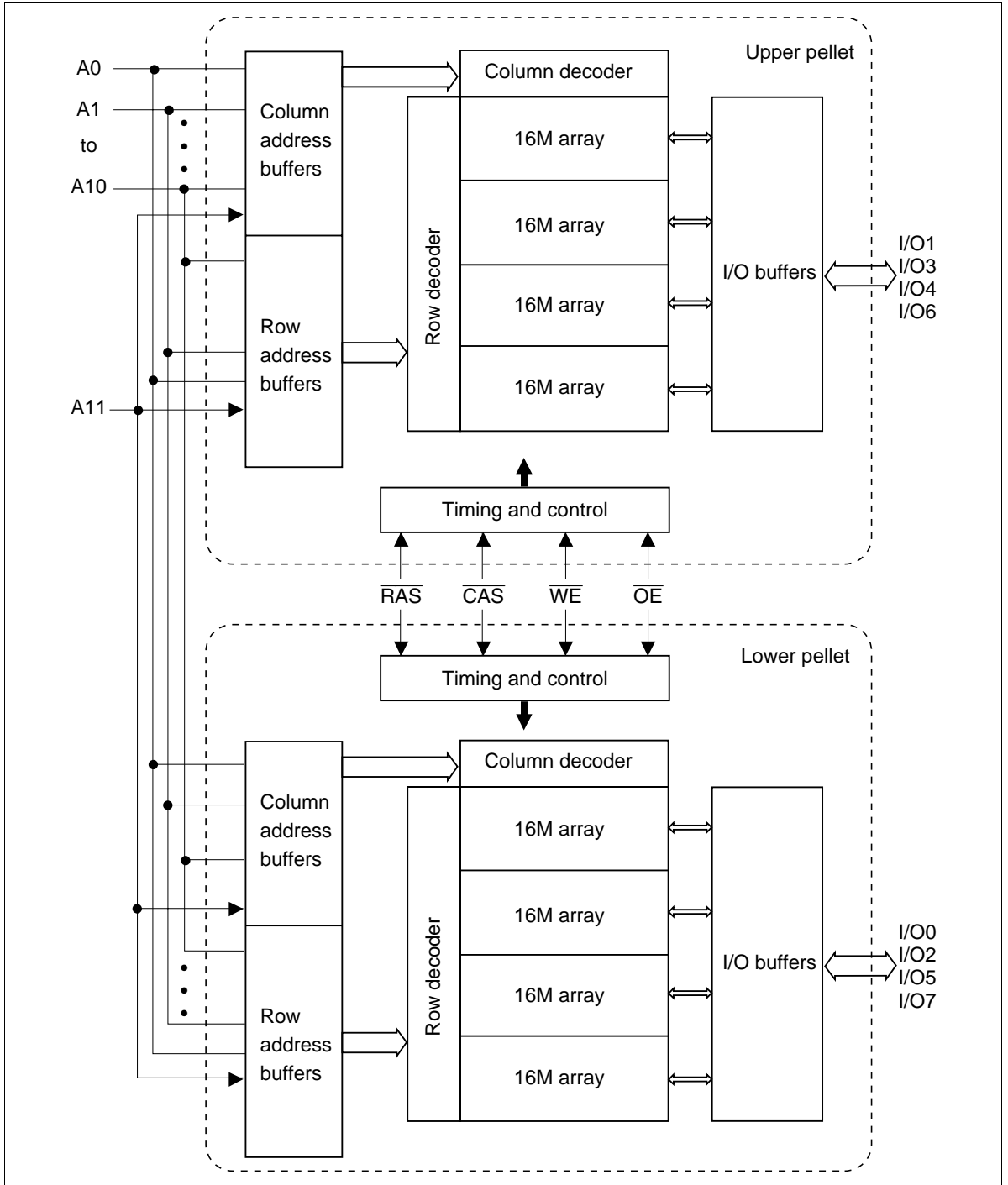
## Pin Description

Pin name	Function
A0 to A11	Address input — Row/Refresh address A0 to A11 — Column address A0 to A11
I/O0 to I/O7	Data input/output
$\overline{\text{RAS}}$	Row address strobe
$\overline{\text{CAS}}$	Column address strobe
$\overline{\text{WE}}$	Write enable
$\overline{\text{OE}}$	Output enable
$V_{\text{CC}}$	Power supply
$V_{\text{SS}}$	Ground
NC	No connection

Block Diagram (HM5112805F)



Block Diagram (HM5113805F)



## Operation Table

$\overline{\text{RAS}}$	$\overline{\text{CAS}}$	$\overline{\text{WE}}$	$\overline{\text{OE}}$	I/O 0 to I/O 7	Operation
H	×	×	×	High-Z	Standby
L	L	H	L	Dout	Read cycle
L	L	L* <sup>2</sup>	×	Din	Early write cycle
L	L	L* <sup>2</sup>	H	Din	Delayed write cycle
L	L	H to L	L to H	Dout/Din	Read-modify-write cycle
L	H	×	×	High-Z	$\overline{\text{RAS}}$ -only refresh cycle
H to L	L	H	×	High-Z	$\overline{\text{CAS}}$ -before- $\overline{\text{RAS}}$ refresh cycle
L	L	H	H	High-Z	Read cycle (Output disabled)

Notes: 1. H:  $V_{IH}$  (inactive), L:  $V_{IL}$  (active), ×:  $V_{IH}$  or  $V_{IL}$

2.  $t_{WCS} \geq 0$  ns: Early write cycle

$t_{WCS} < 0$  ns: Delayed write cycle

## Absolute Maximum Ratings

Parameter	Symbol	Value	Unit
Terminal voltage on any pin relative to $V_{SS}$	$V_T$	-0.5 to $V_{CC} + 0.5$ ( $\leq 4.6$ V (max))	V
Power supply voltage relative to $V_{SS}$	$V_{CC}$	-0.5 to +4.6	V
Short circuit output current	$I_{out}$	50	mA
Power dissipation	$P_T$	1.0	W
Storage temperature	$T_{stg}$	-55 to +125	°C

## DC Operating Conditions

Parameter	Symbol	Min	Typ	Max	Unit	Notes
Supply voltage	$V_{CC}$	3.0	3.3	3.6	V	1, 2
	$V_{SS}$	0	0	0	V	2
Input high voltage	$V_{IH}$	2.0	—	$V_{CC} + 0.3$	V	1
Input low voltage	$V_{IL}$	-0.3	—	0.8	V	1
Ambient temperature range	$T_a$	0	—	70	°C	

Notes: 1. All voltage referred to  $V_{SS}$ .

2. The supply voltage with all  $V_{CC}$  pins must be on the same level. The supply voltage with all  $V_{SS}$  pins must be on the same level.

## DC Characteristics (HM5112805F)

Parameter	Symbol	HM5112805F		Unit	Test conditions
		-6			
		Min	Max		
Operating current <sup>*1, *2</sup>	$I_{CC1}$	—	200	mA	$t_{RC} = \min$
Standby current	$I_{CC2}$	—	4	mA	TTL interface $\overline{RAS}, \overline{CAS} = V_{IH}$ Dout = High-Z
		—	1	mA	CMOS interface $\overline{RAS}, \overline{CAS} \geq V_{CC} - 0.2 V$ Dout = High-Z
Standby current (L-version)	$I_{CC2}$	—	500	$\mu A$	CMOS interface $\overline{RAS}, \overline{CAS} \geq V_{CC} - 0.2 V$ Dout = High-Z
$\overline{RAS}$ -only refresh current <sup>*2</sup>	$I_{CC3}$	—	200	mA	$t_{RC} = \min$
Standby current <sup>*1</sup>	$I_{CC5}$	—	10	mA	$\overline{RAS} = V_{IH}, \overline{CAS} = V_{IL}$ Dout = enable
$\overline{CAS}$ -before- $\overline{RAS}$ refresh current	$I_{CC6}$	—	200	mA	$t_{RC} = \min$
EDO page mode current <sup>*1, *3</sup>	$I_{CC7}$	—	200	mA	$\overline{RAS} = V_{IL}, \overline{CAS}$ cycle, $t_{HPC} = t_{HPC} \min$
Battery backup current <sup>*4</sup> (Standby with CBR refresh) (L-version)	$I_{CC10}$	—	2.5	mA	CMOS interface Dout = High-Z CBR refresh: $t_{RC} = 15.6 \mu s$ $t_{RAS} \leq 0.3 \mu s$
Self refresh mode current (L-version)	$I_{CC11}$	—	1.6	mA	CMOS interface $\overline{RAS}, \overline{CAS} \leq 0.2 V$ Dout = High-Z
Input leakage current	$I_{LI}$	-5	5	$\mu A$	$0 V \leq V_{in} \leq V_{CC} + 0.3 V$
Output leakage current	$I_{LO}$	-5	5	$\mu A$	$0 V \leq V_{out} \leq V_{CC}$ Dout = disable
Output high voltage	$V_{OH}$	2.4	$V_{CC}$	V	High Iout = -2 mA
Output low voltage	$V_{OL}$	0	0.4	V	Low Iout = 2 mA

Notes: 1.  $I_{CC}$  depends on output load condition when the device is selected.  $I_{CC}$  max is specified at the output open condition.

2. Address can be changed once or less while  $\overline{RAS} = V_{IL}$ .

3. Measured with one sequential address change per EDO cycle,  $t_{HPC}$ .

4.  $V_{IH} \geq V_{CC} - 0.2 V, 0 V \leq V_{IL} \leq 0.2 V$ .



**DC Characteristics (HM5113805F)**

Parameter	Symbol	HM5113805F		Unit	Test conditions
		-6			
		Min	Max		
Operating current <sup>*1, *2</sup>	$I_{CC1}$	—	220	mA	$t_{RC} = \text{min}$
Standby current	$I_{CC2}$	—	4	mA	TTL interface $\overline{RAS}, \overline{CAS} = V_{IH}$ Dout = High-Z
		—	1	mA	CMOS interface $\overline{RAS}, \overline{CAS} \geq V_{CC} - 0.2 \text{ V}$ Dout = High-Z
Standby current (L-version)	$I_{CC2}$	—	500	$\mu\text{A}$	CMOS interface $\overline{RAS}, \overline{CAS} \geq V_{CC} - 0.2 \text{ V}$ Dout = High-Z
$\overline{RAS}$ -only refresh current <sup>*2</sup>	$I_{CC3}$	—	220	mA	$t_{RC} = \text{min}$
Standby current <sup>*1</sup>	$I_{CC5}$	—	10	mA	$\overline{RAS} = V_{IH}, \overline{CAS} = V_{IL}$ Dout = enable
$\overline{CAS}$ -before- $\overline{RAS}$ refresh current	$I_{CC6}$	—	220	mA	$t_{RC} = \text{min}$
EDO page mode current <sup>*1, *3</sup>	$I_{CC7}$	—	200	mA	$\overline{RAS} = V_{IL}, \overline{CAS}$ cycle, $t_{HPC} = t_{HPC} \text{ min}$
Battery backup current <sup>*4</sup> (Standby with CBR refresh) (L-version)	$I_{CC10}$	—	2.5	mA	CMOS interface Dout = High-Z CBR refresh: $t_{RC} = 15.6 \mu\text{s}$ $t_{RAS} \leq 0.3 \mu\text{s}$
Self refresh mode current (L-version)	$I_{CC11}$	—	1.6	mA	CMOS interface $\overline{RAS}, \overline{CAS} \leq 0.2 \text{ V}$ Dout = High-Z
Input leakage current	$I_{LI}$	-5	5	$\mu\text{A}$	$0 \text{ V} \leq V_{in} \leq V_{CC} + 0.3 \text{ V}$
Output leakage current	$I_{LO}$	-5	5	$\mu\text{A}$	$0 \text{ V} \leq V_{out} \leq V_{CC}$ Dout = disable
Output high voltage	$V_{OH}$	2.4	$V_{CC}$	V	High Iout = -2 mA
Output low voltage	$V_{OL}$	0	0.4	V	Low Iout = 2 mA

Notes: 1.  $I_{CC}$  depends on output load condition when the device is selected.  $I_{CC}$  max is specified at the output open condition.

2. Address can be changed once or less while  $\overline{RAS} = V_{IL}$ .

3. Measured with one sequential address change per EDO cycle,  $t_{HPC}$ .

4.  $V_{IH} \geq V_{CC} - 0.2 \text{ V}$ ,  $0 \text{ V} \leq V_{IL} \leq 0.2 \text{ V}$ .

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**Capacitance** ( $T_a = 25^\circ\text{C}$ ,  $V_{CC} = 3.3\text{ V} \pm 0.3\text{ V}$ )

Parameter	Symbol	Typ	Max	Unit	Notes
Input capacitance (Address)	$C_{I1}$	—	7	pF	1
Input capacitance (Clocks)	$C_{I2}$	—	7	pF	1
Output capacitance (Data-in, Data-out)	$C_{I/O}$	—	8	pF	1, 2

Notes : 1. Capacitance measured with Boonton Meter or effective capacitance measuring method.

2.  $\overline{\text{RAS}}$  and  $\overline{\text{CAS}} = V_{IH}$  to disable Dout.

**AC Characteristics** ( $T_a = 0$  to  $+70^\circ\text{C}$ ,  $V_{CC} = 3.3\text{ V} \pm 0.3\text{ V}$ ,  $V_{SS} = 0\text{ V}$ ) \*1, \*2, \*19

**Test Conditions**

- Input rise and fall time: 2 ns
- Input pulse levels:  $V_{IL} = 0\text{ V}$ ,  $V_{IH} = 3.0\text{ V}$
- Input timing reference levels: 0.8 V, 2.0 V
- Output timing reference levels: 0.8 V, 2.0 V
- Output load: 1 TTL gate +  $C_L$  (100 pF) (Including scope and jig)

**Read, Write, Read-Modify-Write and Refresh Cycles** (Common parameters)

**HM5112805F/HM5113805F**
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Parameter	Symbol	Min	Max	Unit	Notes
Random read or write cycle time	$t_{RC}$	104	—	ns	
$\overline{\text{RAS}}$ precharge time	$t_{RP}$	40	—	ns	
$\overline{\text{CAS}}$ precharge time	$t_{CP}$	10	—	ns	
$\overline{\text{RAS}}$ pulse width	$t_{RAS}$	60	10000	ns	
$\overline{\text{CAS}}$ pulse width	$t_{CAS}$	10	10000	ns	
Row address setup time	$t_{ASR}$	0	—	ns	
Row address hold time	$t_{RAH}$	10	—	ns	
Column address setup time	$t_{ASC}$	0	—	ns	
Column address hold time	$t_{CAH}$	10	—	ns	
$\overline{\text{RAS}}$ to $\overline{\text{CAS}}$ delay time	$t_{RCD}$	14	45	ns	3
$\overline{\text{RAS}}$ to column address delay time	$t_{RAD}$	12	30	ns	4
$\overline{\text{RAS}}$ hold time	$t_{RSH}$	15	—	ns	
$\overline{\text{CAS}}$ hold time	$t_{CSH}$	40	—	ns	
$\overline{\text{CAS}}$ to $\overline{\text{RAS}}$ precharge time	$t_{CRP}$	5	—	ns	
$\overline{\text{OE}}$ to Din delay time	$t_{OED}$	15	—	ns	5
$\overline{\text{OE}}$ delay time from Din	$t_{DZO}$	0	—	ns	6
$\overline{\text{CAS}}$ delay time from Din	$t_{DZC}$	0	—	ns	6
Transition time (rise and fall)	$t_T$	2	50	ns	7

## Read Cycle

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Parameter	Symbol	Min	Max	Unit	Notes
Access time from $\overline{\text{RAS}}$	$t_{\text{RAC}}$	—	60	ns	8, 9
Access time from $\overline{\text{CAS}}$	$t_{\text{CAC}}$	—	15	ns	9, 10, 17
Access time from address	$t_{\text{AA}}$	—	30	ns	9, 11, 17
Access time from $\overline{\text{OE}}$	$t_{\text{OEA}}$	—	15	ns	9
Read command setup time	$t_{\text{RCS}}$	0	—	ns	
Read command hold time to $\overline{\text{CAS}}$	$t_{\text{RCH}}$	0	—	ns	12
Read command hold time from $\overline{\text{RAS}}$	$t_{\text{RCHR}}$	60	—	ns	
Read command hold time to $\overline{\text{RAS}}$	$t_{\text{RRH}}$	0	—	ns	12
Column address to $\overline{\text{RAS}}$ lead time	$t_{\text{RAL}}$	30	—	ns	
Column address to $\overline{\text{CAS}}$ lead time	$t_{\text{CAL}}$	18	—	ns	
$\overline{\text{CAS}}$ to output in low-Z	$t_{\text{CLZ}}$	0	—	ns	
Output data hold time	$t_{\text{OH}}$	3	—	ns	21
Output data hold time from $\overline{\text{OE}}$	$t_{\text{OHO}}$	3	—	ns	
Output buffer turn-off time	$t_{\text{OFF}}$	—	15	ns	13, 21
Output buffer turn-off to $\overline{\text{OE}}$	$t_{\text{OEZ}}$	—	15	ns	13
$\overline{\text{CAS}}$ to Din delay time	$t_{\text{CDD}}$	15	—	ns	5
Output data hold time from $\overline{\text{RAS}}$	$t_{\text{OHR}}$	3	—	ns	21
Output buffer turn-off to $\overline{\text{RAS}}$	$t_{\text{OFR}}$	—	15	ns	13, 21
Output buffer turn-off to $\overline{\text{WE}}$	$t_{\text{WEZ}}$	—	15	ns	13
$\overline{\text{WE}}$ to Din delay time	$t_{\text{WED}}$	15	—	ns	
$\overline{\text{RAS}}$ to Din delay time	$t_{\text{RDD}}$	15	—	ns	

## Write Cycle

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Parameter	Symbol	Min	Max	Unit	Notes
Write command setup time	$t_{WCS}$	0	—	ns	14
Write command hold time	$t_{WCH}$	10	—	ns	
Write command pulse width	$t_{WP}$	10	—	ns	
Write command to $\overline{RAS}$ lead time	$t_{RWL}$	15	—	ns	
Write command to $\overline{CAS}$ lead time	$t_{CWL}$	10	—	ns	
Data-in setup time	$t_{DS}$	0	—	ns	15
Data-in hold time	$t_{DH}$	10	—	ns	15

## Read-Modify-Write Cycle

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Parameter	Symbol	Min	Max	Unit	Notes
Read-modify-write cycle time	$t_{RWC}$	140	—	ns	
$\overline{RAS}$ to $\overline{WE}$ delay time	$t_{RWD}$	79	—	ns	14
$\overline{CAS}$ to $\overline{WE}$ delay time	$t_{CWD}$	34	—	ns	14
Column address to $\overline{WE}$ delay time	$t_{AWD}$	49	—	ns	14
$\overline{OE}$ hold time from $\overline{WE}$	$t_{OEH}$	15	—	ns	

## Refresh Cycle

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Parameter	Symbol	Min	Max	Unit	Notes
$\overline{CAS}$ setup time (CBR refresh cycle)	$t_{CSR}$	5	—	ns	
$\overline{CAS}$ hold time (CBR refresh cycle)	$t_{CHR}$	10	—	ns	
$\overline{WE}$ setup time (CBR refresh cycle)	$t_{WRP}$	0	—	ns	
$\overline{WE}$ hold time (CBR refresh cycle)	$t_{WRH}$	10	—	ns	
$\overline{RAS}$ precharge to $\overline{CAS}$ hold time	$t_{RPC}$	5	—	ns	

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## EDO Page Mode Cycle

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Parameter	Symbol	Min	Max	Unit	Notes
EDO page mode cycle time	$t_{HPC}$	25	—	ns	20
EDO page mode $\overline{RAS}$ pulse width	$t_{RASP}$	—	100000	ns	16
Access time from $\overline{CAS}$ precharge	$t_{CPA}$	—	35	ns	9, 17
$\overline{RAS}$ hold time from $\overline{CAS}$ precharge	$t_{CPRH}$	35	—	ns	
Output data hold time from $\overline{CAS}$ low	$t_{DOH}$	3	—	ns	9, 22
$\overline{CAS}$ hold time referred $\overline{OE}$	$t_{COL}$	10	—	ns	
$\overline{CAS}$ to $\overline{OE}$ setup time	$t_{COP}$	5	—	ns	
Read command hold time from $\overline{CAS}$ precharge	$t_{RCHC}$	35	—	ns	
Write pulse width during $\overline{CAS}$ precharge	$t_{WPE}$	10	—	ns	
$\overline{OE}$ precharge time	$t_{OEP}$	10	—	ns	

## EDO Page Mode Read-Modify-Write Cycle

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Parameter	Symbol	Min	Max	Unit	Notes
EDO page mode read-modify-write cycle time	$t_{HPRWC}$	68	—	ns	
$\overline{WE}$ delay time from $\overline{CAS}$ precharge	$t_{CPW}$	54	—	ns	14

## Refresh(HM5112805F)

Parameter	Symbol	Max	Unit	Notes
Refresh period	$t_{REF}$	64	ms	8192 cycles
Refresh period (L-version)	$t_{REF}$	64	ms	8192 cycles

## Refresh(HM5113805F)

Parameter	Symbol	Max	Unit	Notes
Refresh period	$t_{REF}$	64	ms	4096 cycles
Refresh period (L-version)	$t_{REF}$	64	ms	4096 cycles

**Self Refresh Mode (L-version)**

Parameter	Symbol	HM5112805FL/HM5113805FL		Unit	Notes
		Min	Max		
$\overline{\text{RAS}}$ pulse width (self refresh)	$t_{\text{RASS}}$	100	—	$\mu\text{s}$	25
$\overline{\text{RAS}}$ precharge time (self refresh)	$t_{\text{RPS}}$	110	—	ns	25
$\overline{\text{CAS}}$ hold time (self refresh)	$t_{\text{CHS}}$	-50	—	ns	

Notes: 1. AC measurements assume  $t_f = 2$  ns.

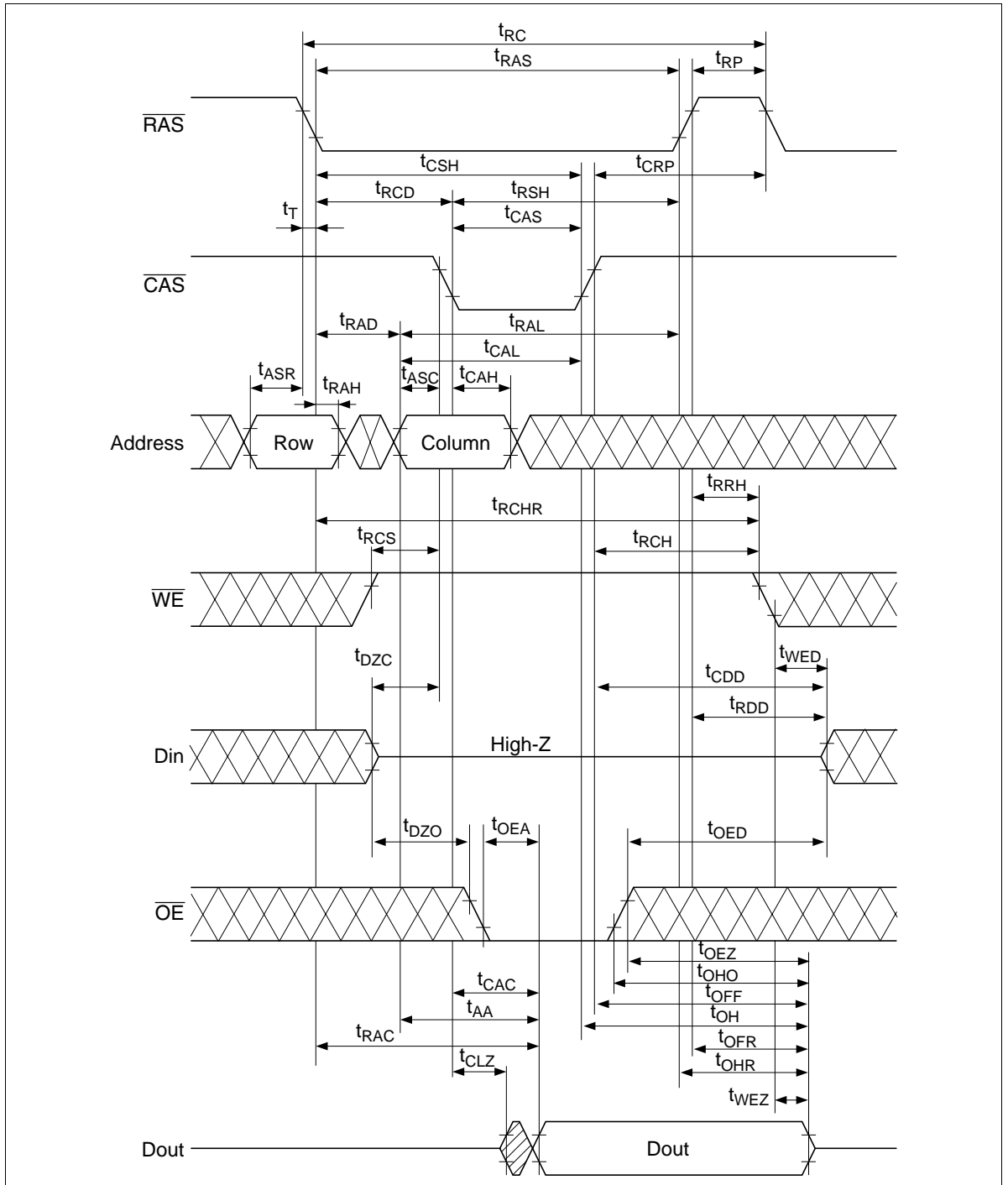
2. An initial pause of 200  $\mu\text{s}$  is required after power up followed by a minimum of eight initialization cycles (any combination of cycles containing  $\overline{\text{RAS}}$ -only refresh or  $\overline{\text{CAS}}$ -before- $\overline{\text{RAS}}$  refresh).
3. Operation with the  $t_{\text{RCD}}$  (max) limit insures that  $t_{\text{RAC}}$  (max) can be met,  $t_{\text{RCD}}$  (max) is specified as a reference point only; if  $t_{\text{RCD}}$  is greater than the specified  $t_{\text{RCD}}$  (max) limit, then the access time is controlled exclusively by  $t_{\text{CAC}}$ .
4. Operation with the  $t_{\text{RAD}}$  (max) limit insures that  $t_{\text{RAC}}$  (max) can be met,  $t_{\text{RAD}}$  (max) is specified as a reference point only; if  $t_{\text{RAD}}$  is greater than the specified  $t_{\text{RAD}}$  (max) limit, then access time is controlled exclusively by  $t_{\text{AA}}$ .
5. Either  $t_{\text{OED}}$  or  $t_{\text{CDD}}$  must be satisfied.
6. Either  $t_{\text{DZO}}$  or  $t_{\text{DZC}}$  must be satisfied.
7.  $V_{\text{IH}}$  (min) and  $V_{\text{IL}}$  (max) are reference levels for measuring timing of input signals. Also, transition times are measured between  $V_{\text{IH}}$  (min) and  $V_{\text{IL}}$  (max).
8. Assumes that  $t_{\text{RCD}} \leq t_{\text{RCD}}$  (max) and  $t_{\text{RAD}} \leq t_{\text{RAD}}$  (max). If  $t_{\text{RCD}}$  or  $t_{\text{RAD}}$  is greater than the maximum recommended value shown in this table,  $t_{\text{RAC}}$  exceeds the value shown.
9. Measured with a load circuit equivalent to 1 TTL loads and 100 pF.
10. Assumes that  $t_{\text{RCD}} \geq t_{\text{RCD}}$  (max) and  $t_{\text{RCD}} + t_{\text{CAC}}$  (max)  $\geq t_{\text{RAD}} + t_{\text{AA}}$  (max).
11. Assumes that  $t_{\text{RAD}} \geq t_{\text{RAD}}$  (max) and  $t_{\text{RCD}} + t_{\text{CAC}}$  (max)  $\leq t_{\text{RAD}} + t_{\text{AA}}$  (max).
12. Either  $t_{\text{RCH}}$  or  $t_{\text{RRH}}$  must be satisfied for a read cycles.
13.  $t_{\text{OFF}}$  (max),  $t_{\text{OEZ}}$  (max),  $t_{\text{WEZ}}$  (max) and  $t_{\text{OFR}}$  (max) define the time at which the outputs achieve the open circuit condition and are not referred to output voltage levels.
14.  $t_{\text{WCS}}$ ,  $t_{\text{RWD}}$ ,  $t_{\text{CWD}}$ ,  $t_{\text{AWD}}$  and  $t_{\text{CPW}}$  are not restrictive operating parameters. They are included in the data sheet as electrical characteristics only; if  $t_{\text{WCS}} \geq t_{\text{WCS}}$  (min), the cycle is an early write cycle and the data out pin will remain open circuit (high impedance) throughout the entire cycle; if  $t_{\text{RWD}} \geq t_{\text{RWD}}$  (min),  $t_{\text{CWD}} \geq t_{\text{CWD}}$  (min), and  $t_{\text{AWD}} \geq t_{\text{AWD}}$  (min), or  $t_{\text{CWD}} \geq t_{\text{CWD}}$  (min),  $t_{\text{AWD}} \geq t_{\text{AWD}}$  (min) and  $t_{\text{CPW}} \geq t_{\text{CPW}}$  (min), the cycle is a read-modify-write and the data output will contain data read from the selected cell; if neither of the above sets of conditions is satisfied, the condition of the data out (at access time) is indeterminate.
15.  $t_{\text{DS}}$  and  $t_{\text{DH}}$  are referred to  $\overline{\text{CAS}}$  leading edge in early write cycles and to  $\overline{\text{WE}}$  leading edge in delayed write or read-modify-write cycles.
16.  $t_{\text{RASP}}$  defines  $\overline{\text{RAS}}$  pulse width in EDO page mode cycles.
17. Access time is determined by the longest among  $t_{\text{AA}}$ ,  $t_{\text{CAC}}$  and  $t_{\text{CPA}}$ .
18. In delayed write or read-modify-write cycles,  $\overline{\text{OE}}$  must disable output buffer prior to applying data to the device.
19. When output buffers are enabled once, sustain the low impedance state until valid data is obtained. When output buffer is turned on and off within a very short time, generally it causes large  $V_{\text{CC}}/V_{\text{SS}}$  line noise, which causes to degrade  $V_{\text{IH}}$  min/ $V_{\text{IL}}$  max level.

20.  $t_{\text{HPC}}$  (min) can be achieved during a series of EDO page mode write cycles or EDO page mode read cycles. If both write and read operation are mixed in a EDO page mode RAS cycle (EDO page mode mix cycle (1), (2)), minimum value of  $\overline{\text{CAS}}$  cycle ( $t_{\text{CAS}} + t_{\text{CP}} + 2 t_{\text{T}}$ ) becomes greater than the specified  $t_{\text{HPC}}$  (min) value. The value of  $\overline{\text{CAS}}$  cycle time of mixed EDO page mode is shown in EDO page mode mix cycle (1) and (2).
21. Data output turns off and becomes high impedance from later rising edge of  $\overline{\text{RAS}}$  and  $\overline{\text{CAS}}$ . Hold time and turn off time are specified by the timing specifications of later rising edge of  $\overline{\text{RAS}}$  and  $\overline{\text{CAS}}$  between  $t_{\text{OHR}}$  and  $t_{\text{OH}}$  and between  $t_{\text{OFR}}$  and  $t_{\text{OFF}}$ .
22.  $t_{\text{DOH}}$  defines the time at which the output level go cross.  $V_{\text{OL}} = 0.8 \text{ V}$ ,  $V_{\text{OH}} = 2.0 \text{ V}$  of output timing reference level.
23. Before and after self refresh mode, execute CBR refresh to all refresh addresses in or within 64 ms period on the condition a and b below.
  - a. Enter self refresh mode within 15.6  $\mu\text{s}$  after either burst refresh or distributed refresh at equal interval to all refresh addresses are completed.
  - b. Start burst refresh or distributed refresh at equal interval to all refresh addresses within 15.6 $\mu\text{s}$  after exiting from self refresh mode.
24. In case of entering from  $\overline{\text{RAS}}$ -only-refresh, it is necessary to execute CBR refresh before and after self refresh mode according as note 23.
25. At  $t_{\text{RASS}} > 100 \mu\text{s}$ , self refresh mode is activated, and not activated at  $t_{\text{RASS}} < 10 \mu\text{s}$ . It is undefined within the range of  $10 \mu\text{s} \leq t_{\text{RASS}} \leq 100 \mu\text{s}$ . For  $t_{\text{RASS}} \geq 10 \mu\text{s}$ , it is necessary to satisfy  $t_{\text{RPS}}$ .
26. XXX: H or L (H:  $V_{\text{IH}}(\text{min}) \leq V_{\text{IN}} \leq V_{\text{IH}}(\text{max})$ , L:  $V_{\text{IL}}(\text{min}) \leq V_{\text{IN}} \leq V_{\text{IL}}(\text{max})$ )  
/////: Invalid Dout  
When the address, clock and input pins are not described on timing waveforms, their pins must be applied  $V_{\text{IH}}$  or  $V_{\text{IL}}$ .

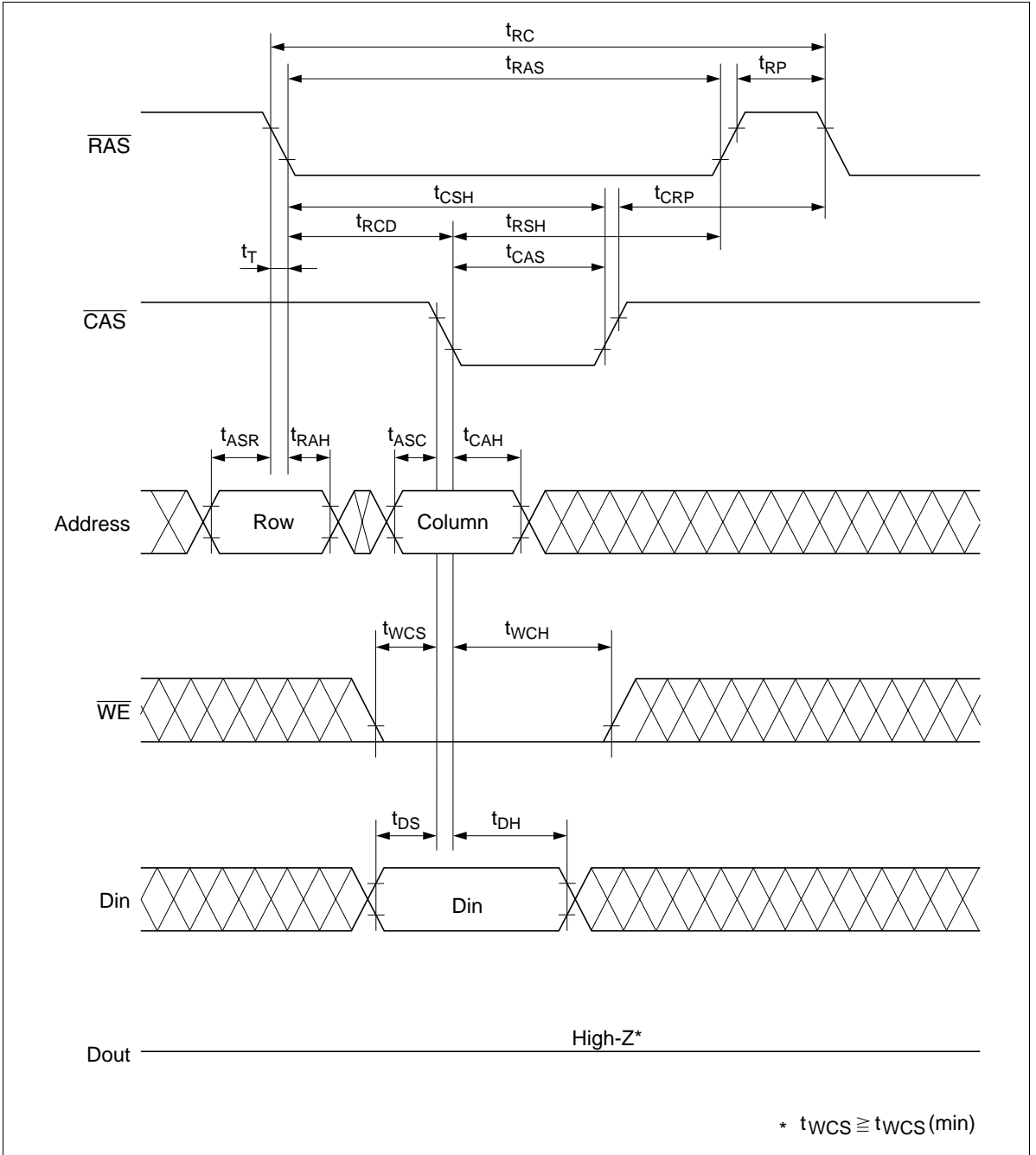


Timing Waveforms\*26

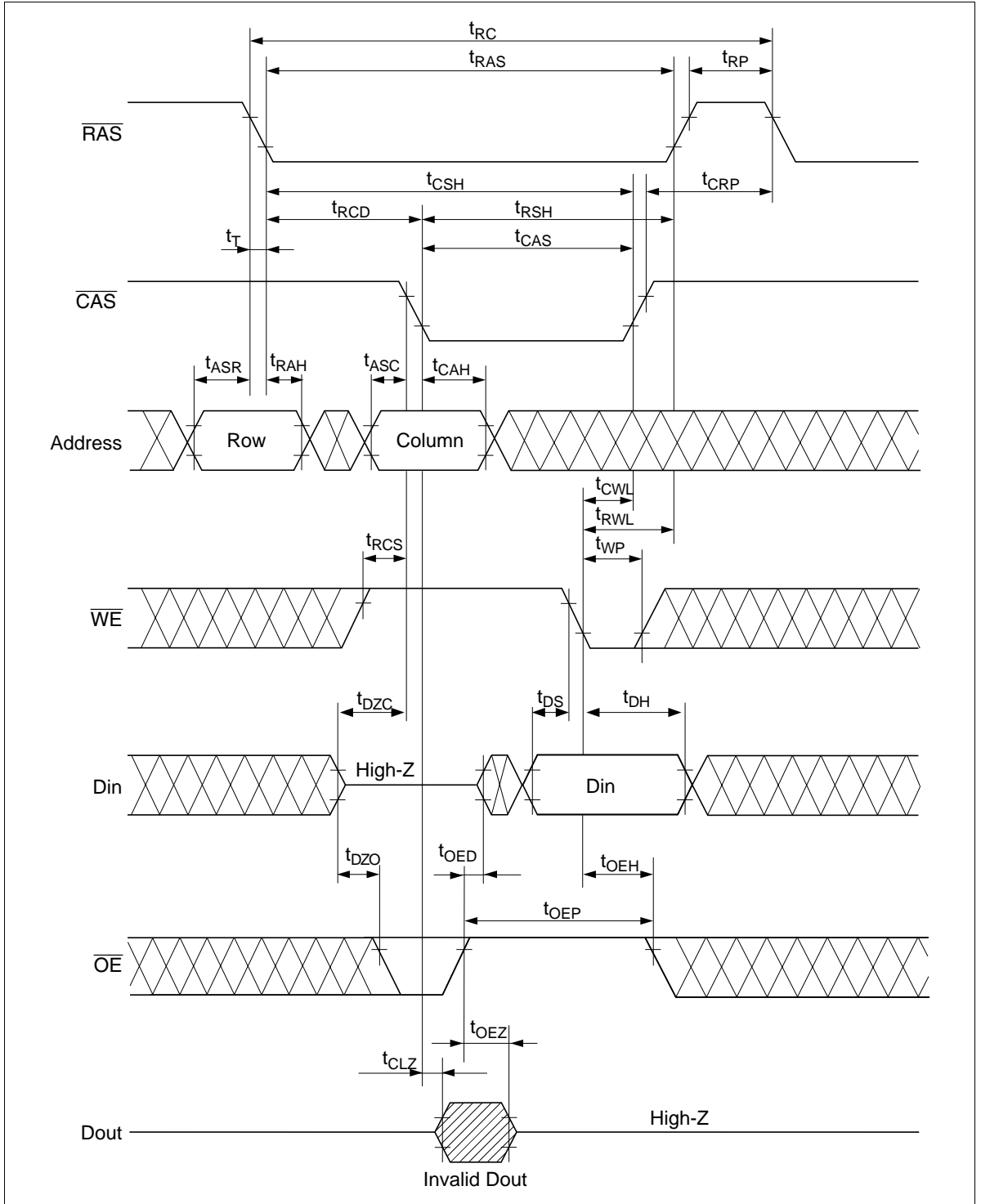
Read Cycle



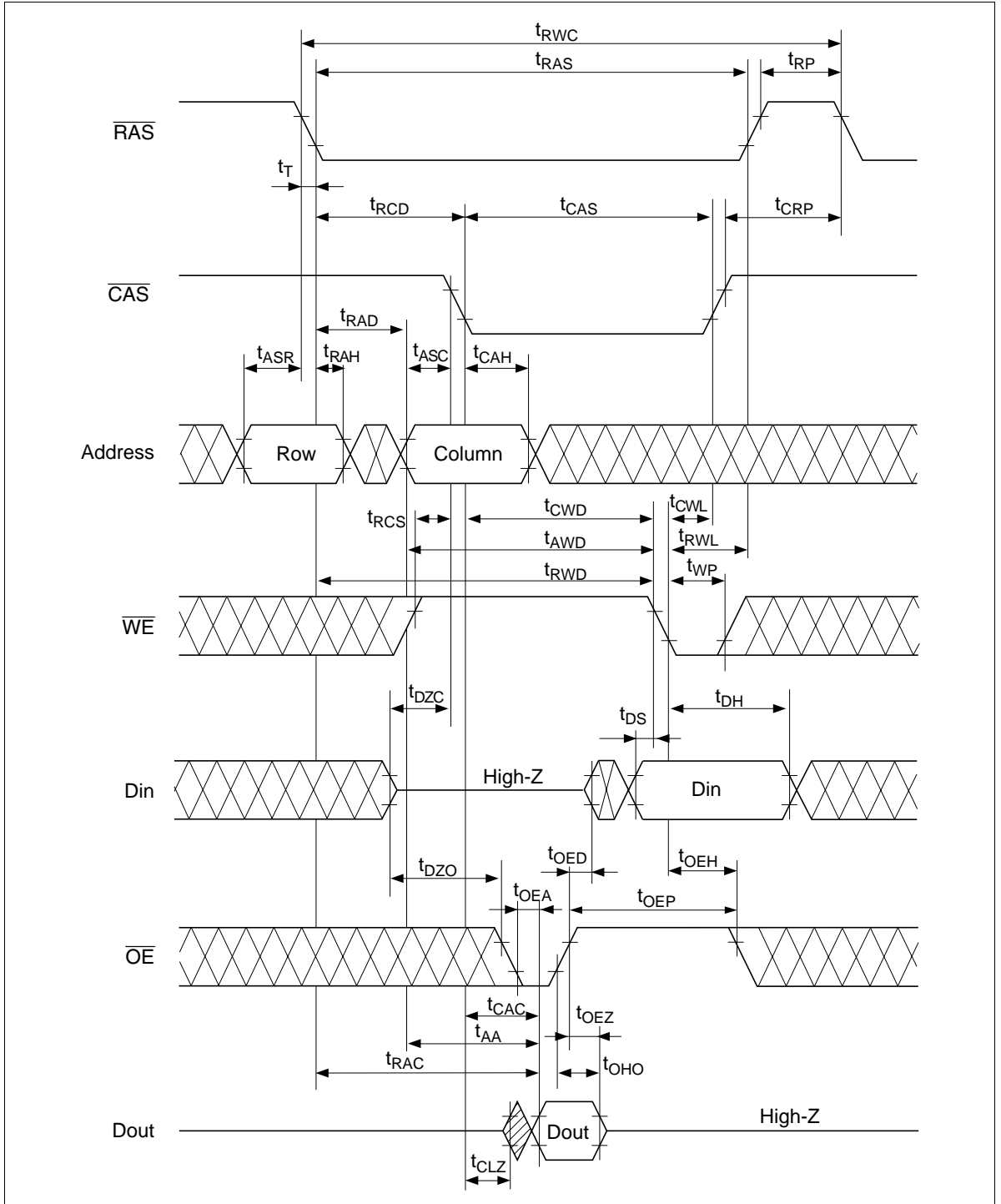
Early Write Cycle



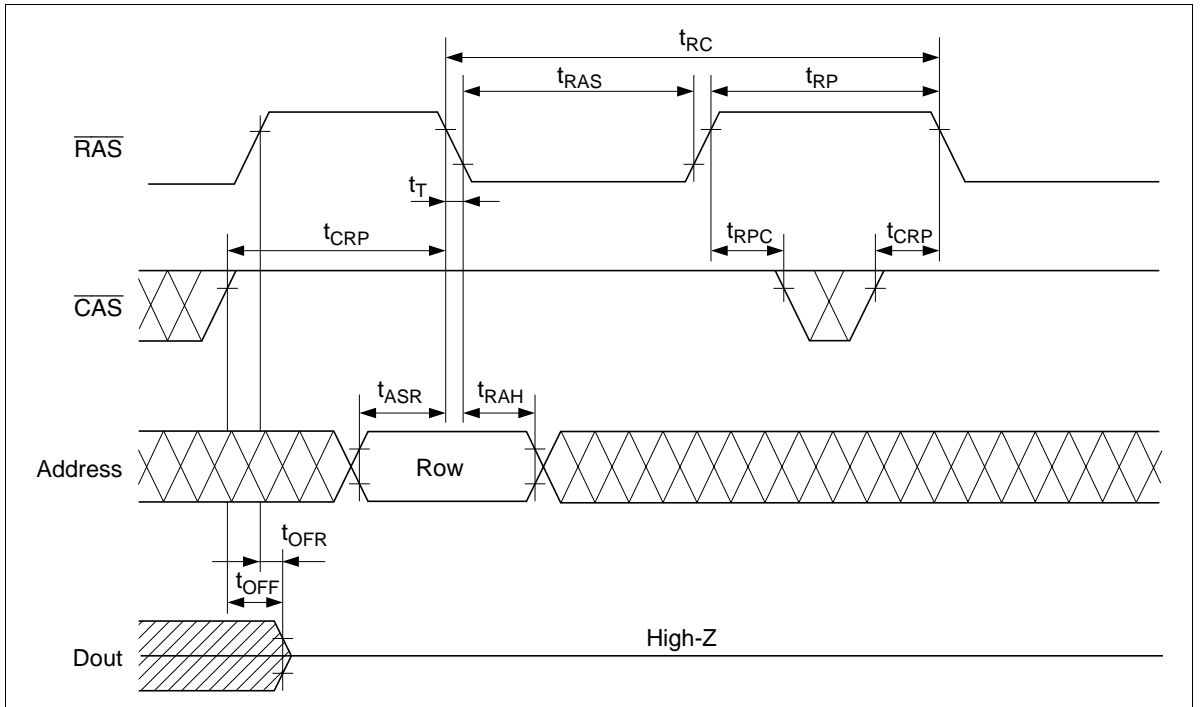
Delayed Write Cycle\*18



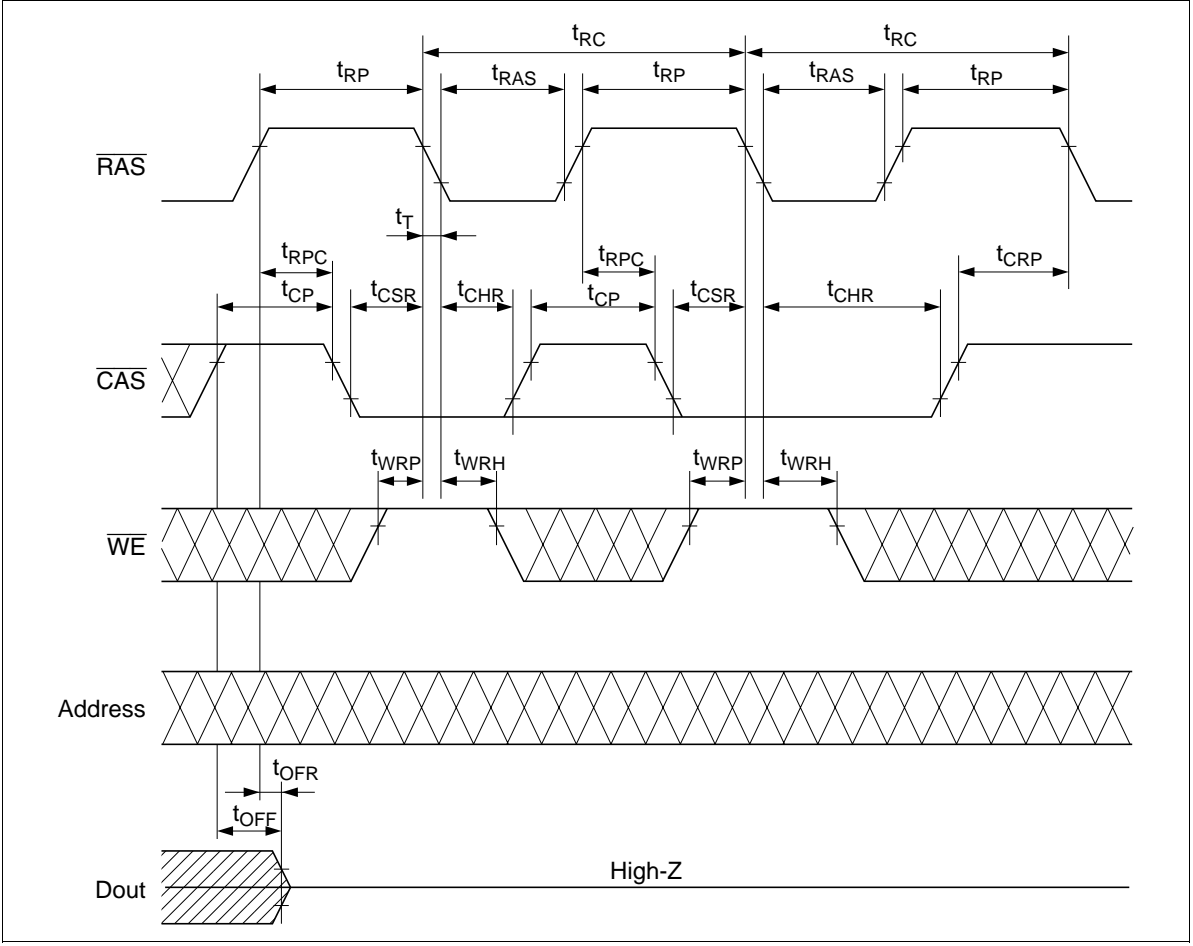
Read-Modify-Write Cycle\*18



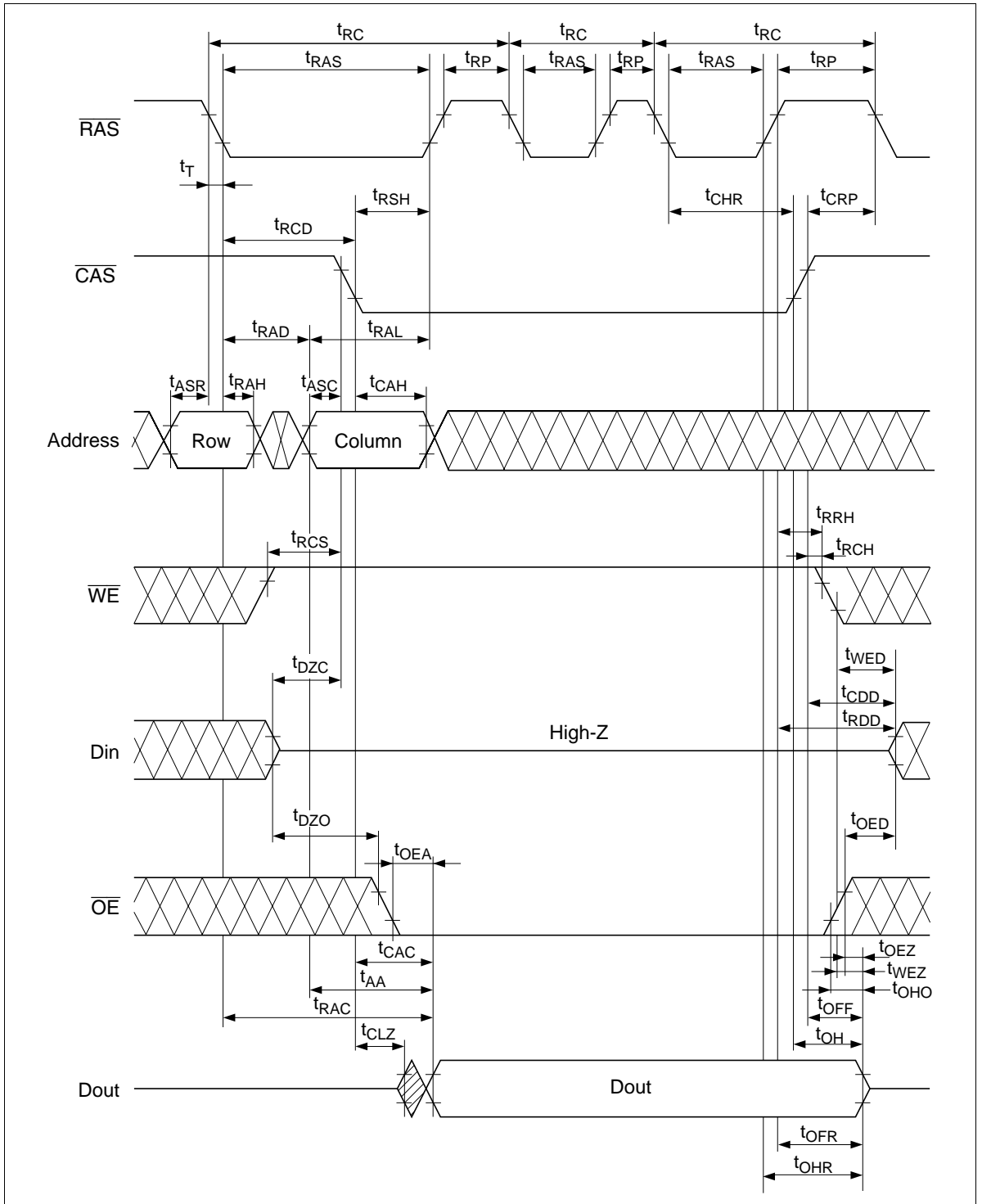
RAS-Only Refresh Cycle



$\overline{\text{CAS}}$ -Before- $\overline{\text{RAS}}$  Refresh Cycle



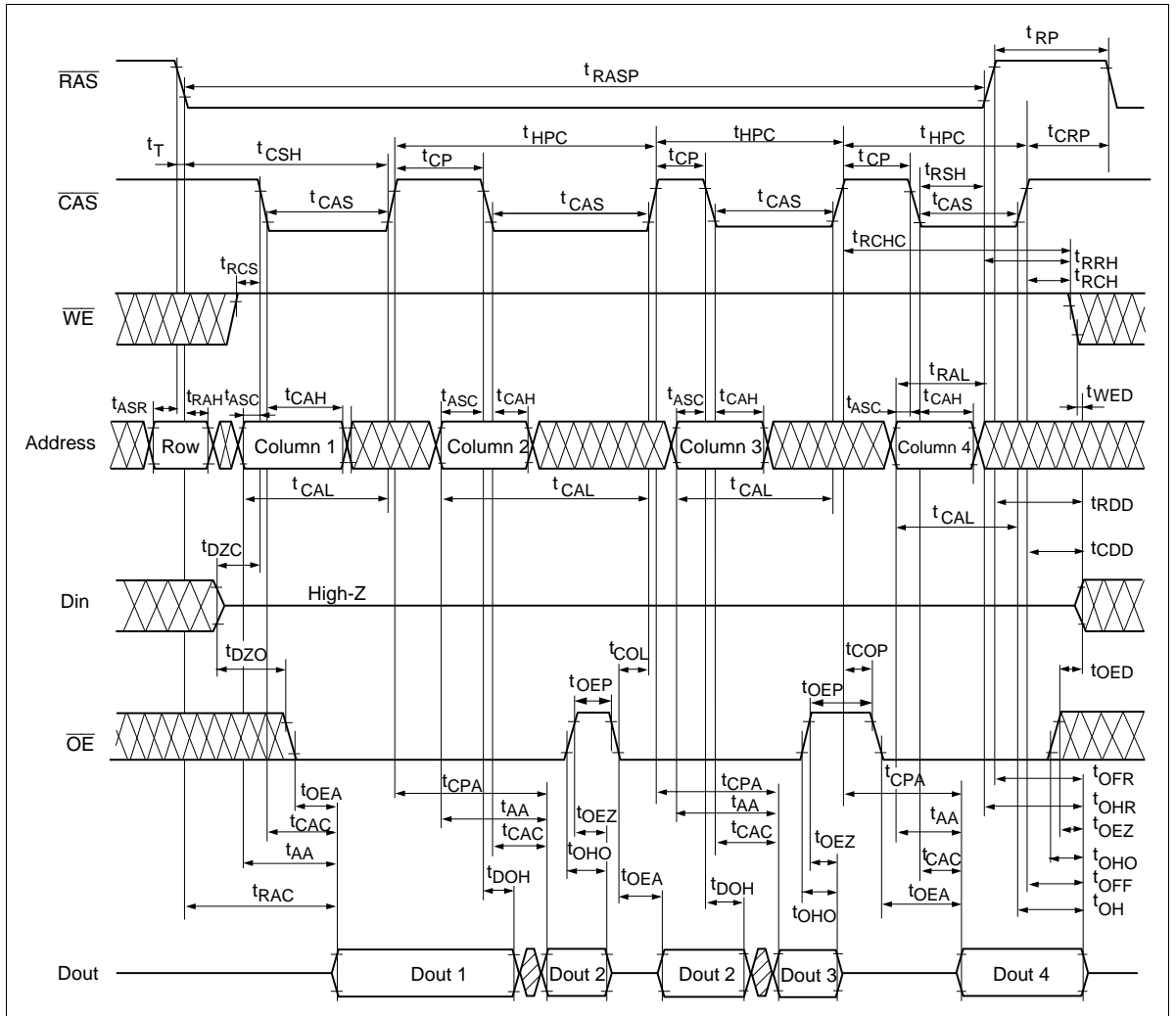
Hidden Refresh Cycle



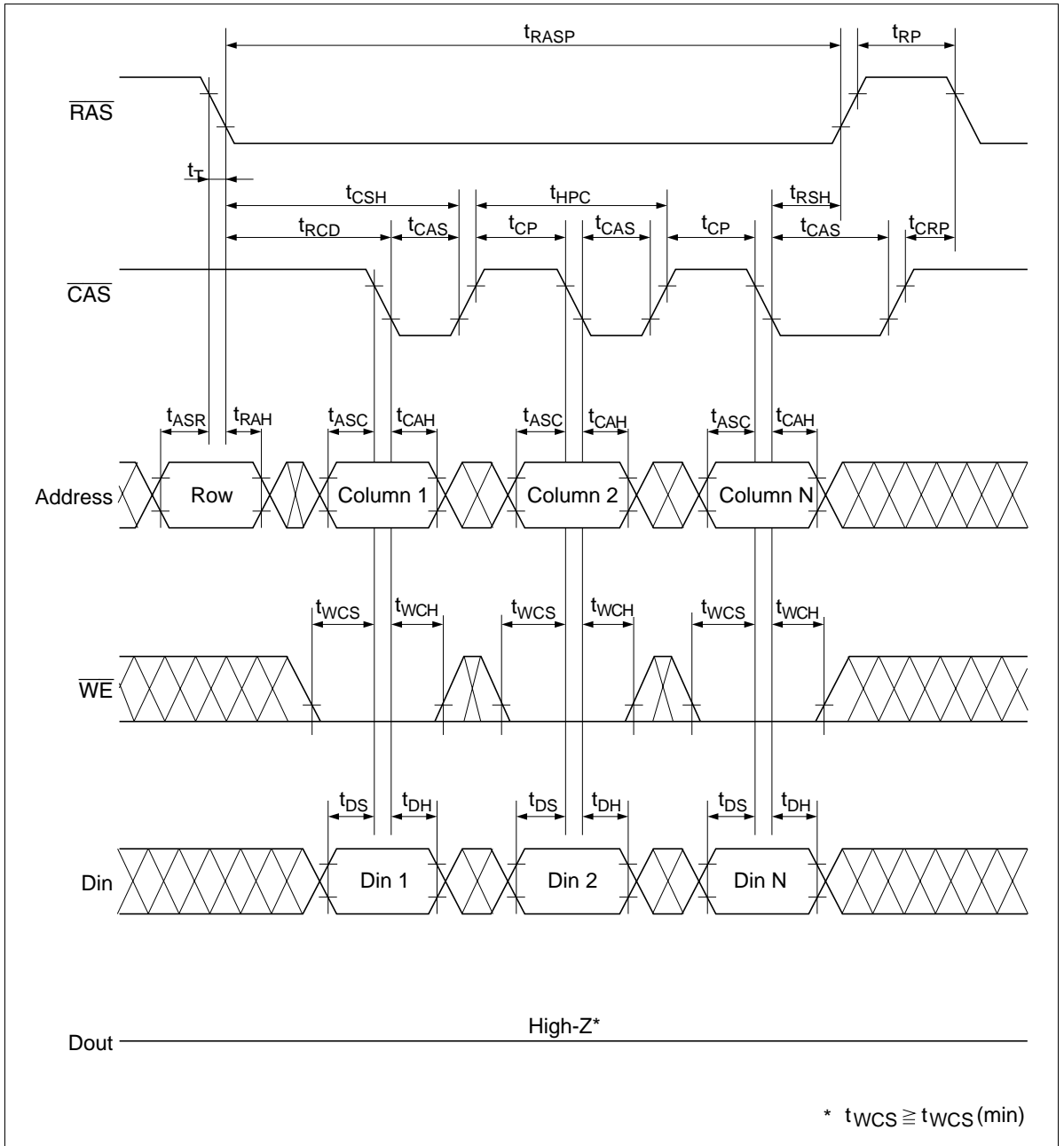




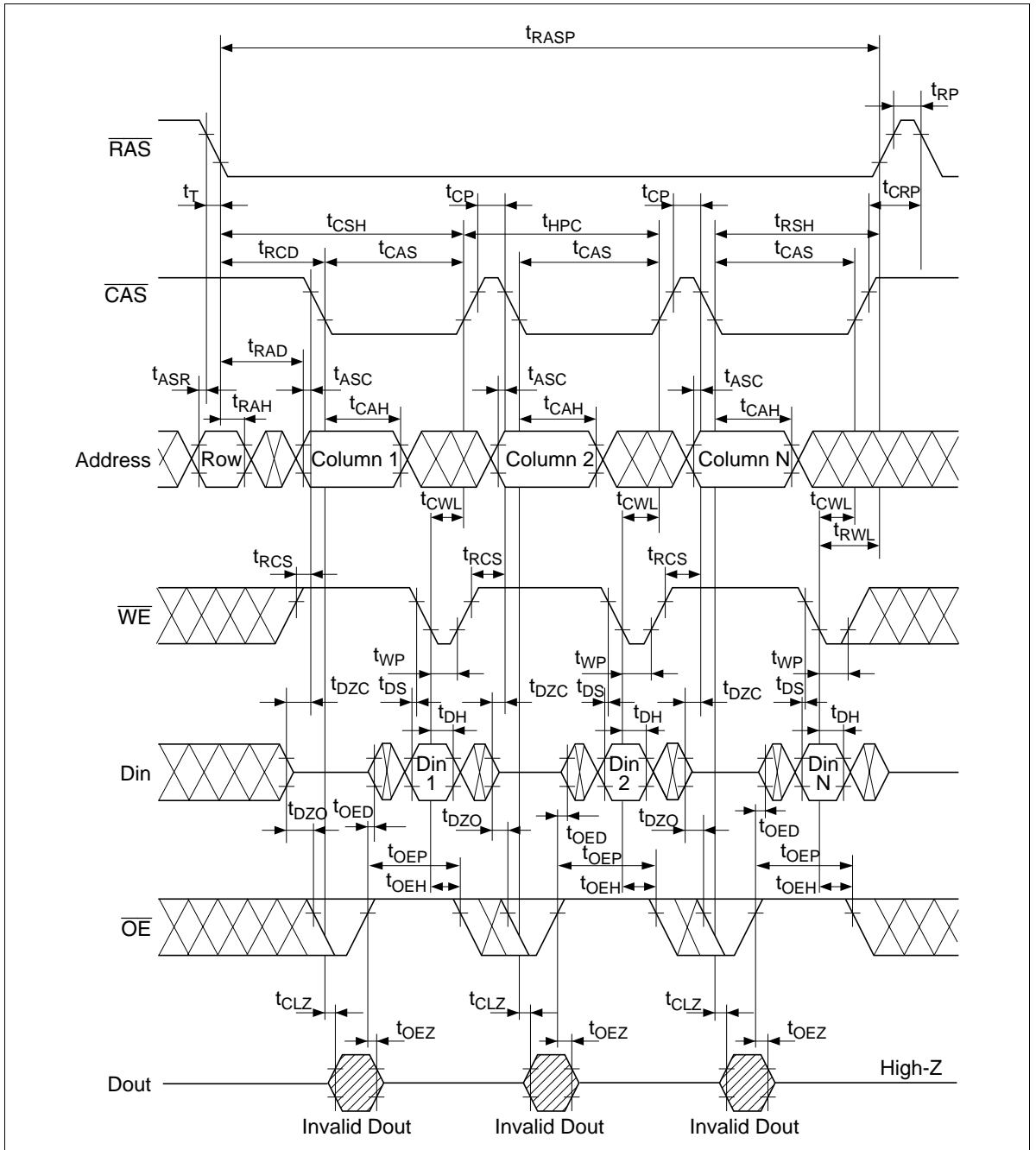
EDO Page Mode Read Cycle (2)



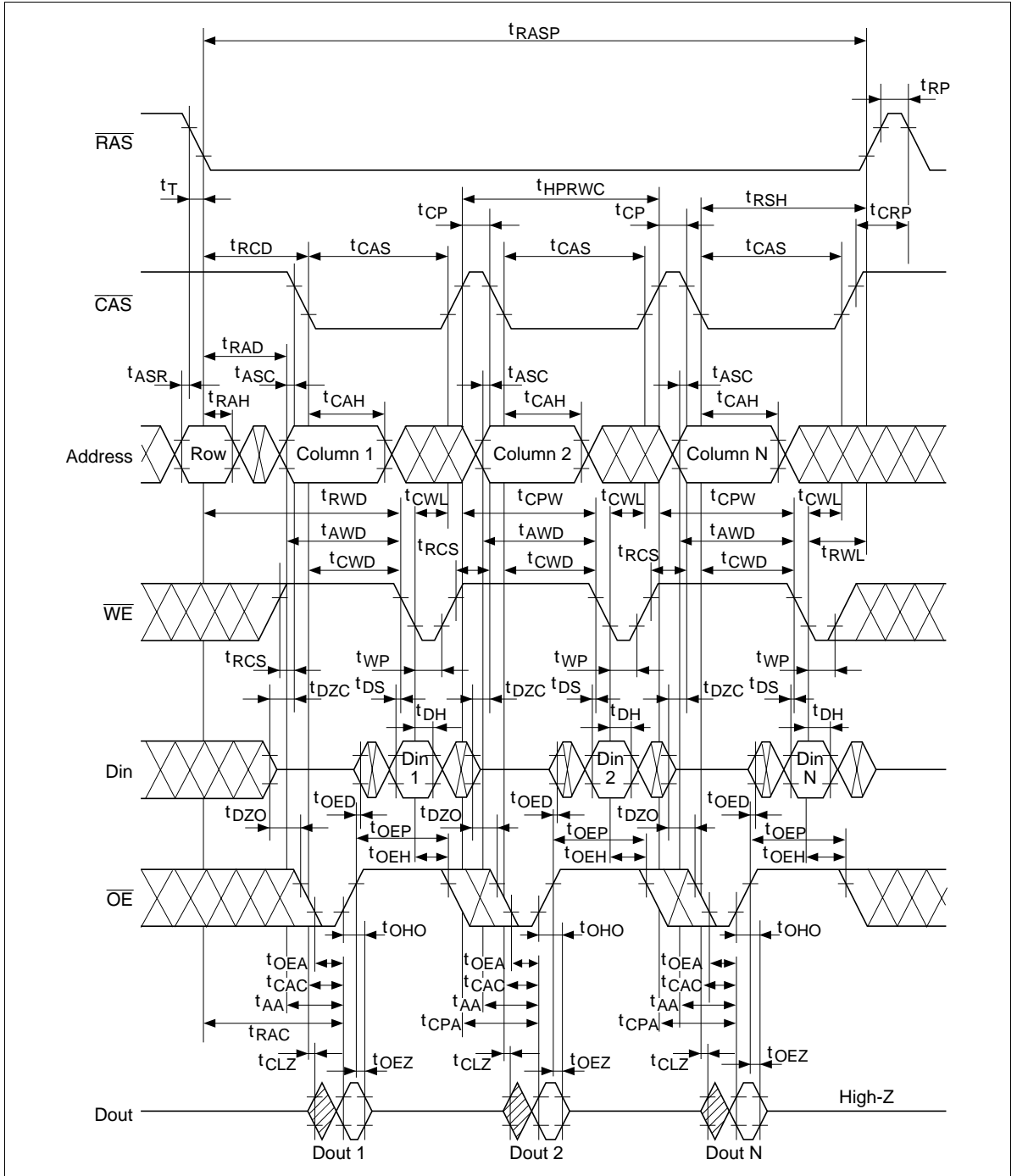
EDO Page Mode Early Write Cycle



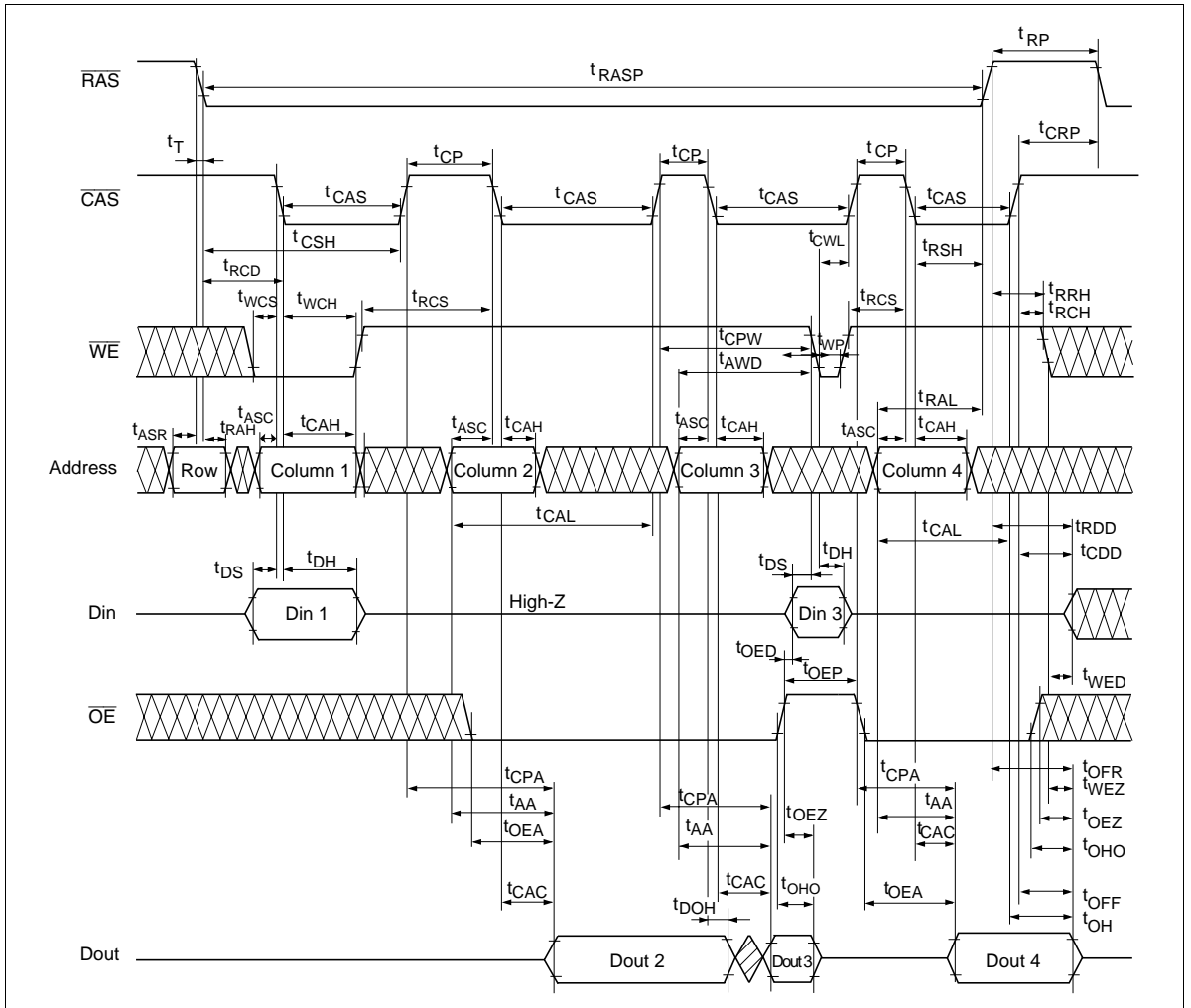
EDO Page Mode Delayed Write Cycle\*18



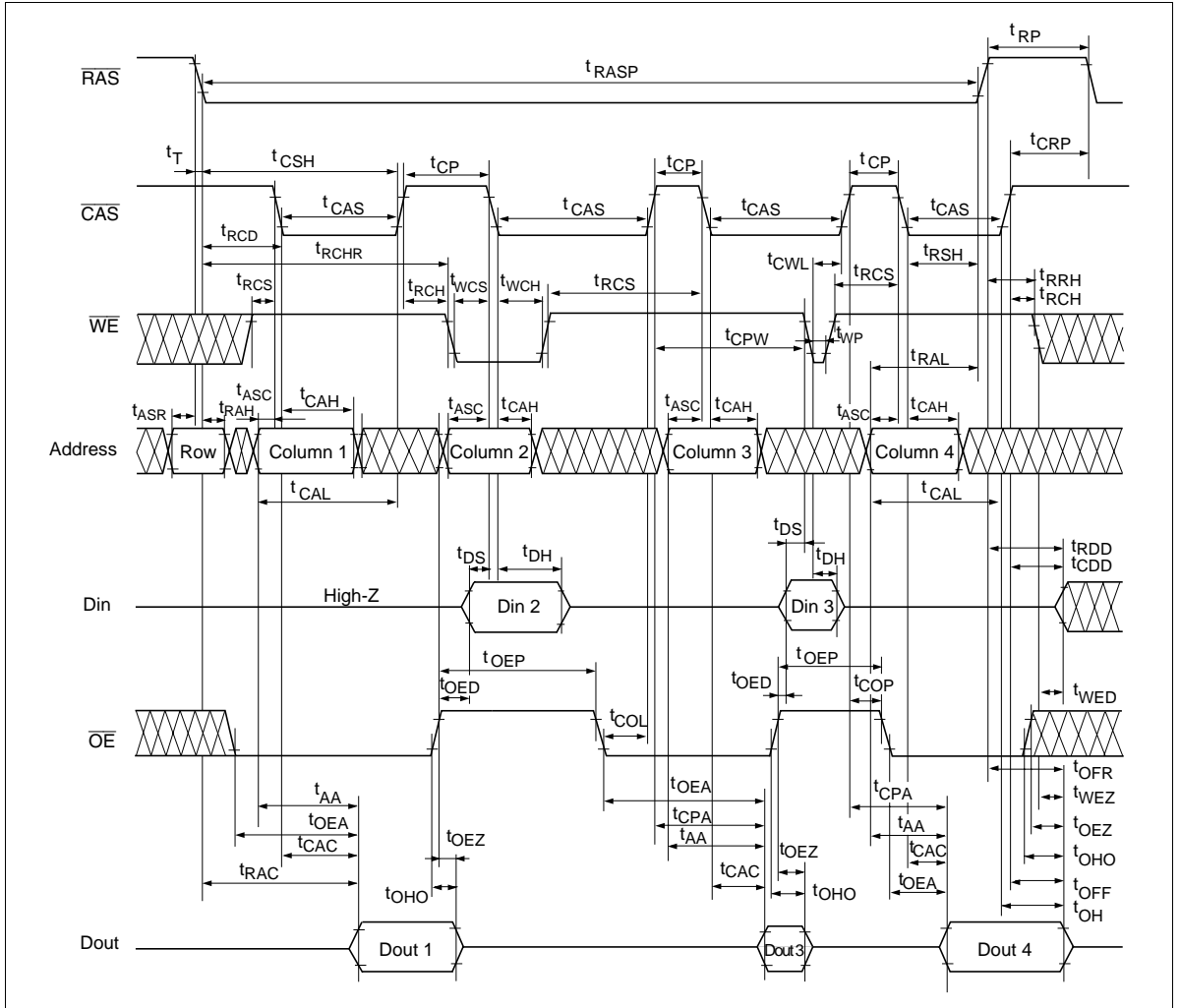
EDO Page Mode Read-Modify-Write Cycle\*18



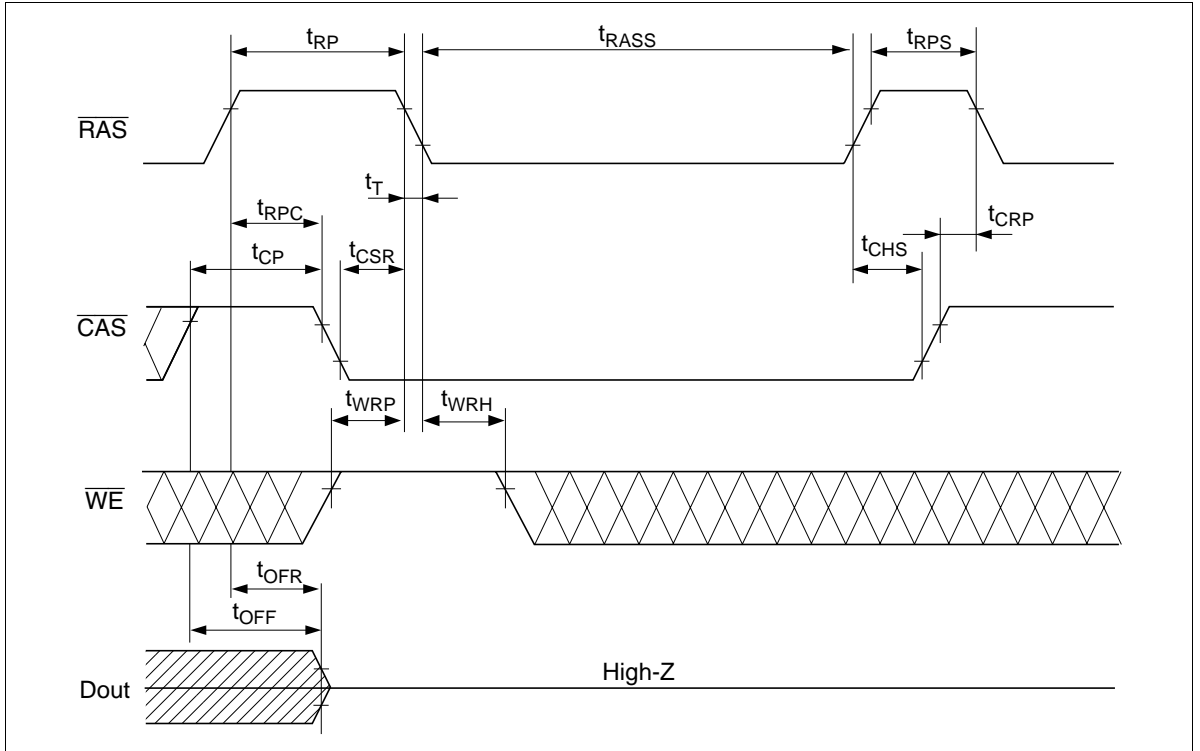
EDO Page Mode Mix Cycle (1)\*20



EDO Page Mode Mix Cycle (2) \*20



Self Refresh Cycle (L-version)\* 23, 24, 25

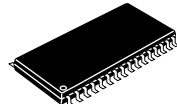
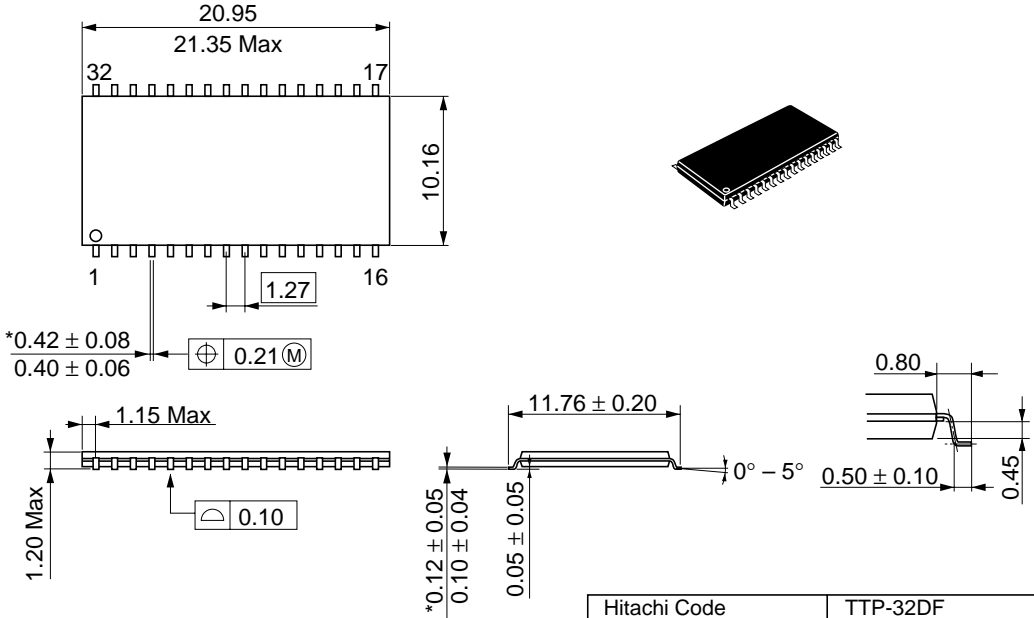


Package Dimensions

HM5112805FTD/FLTD

HM5113805FTD/FLTD (TTP-32DF)

Unit: mm



\*Dimension including the plating thickness  
Base material dimension

Hitachi Code	TTP-32DF
JEDEC	—
EIAJ	—
Weight (reference value)	0.54 g



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# HITACHI

## Hitachi, Ltd.

Semiconductor & Integrated Circuits.

Nippon Bldg., 2-6-2, Ohite-machi, Chiyoda-ku, Tokyo 100-0004, Japan

Tel: Tokyo (03) 3270-2111 Fax: (03) 3270-5109

URL      NorthAmerica      : <http://semiconductor.hitachi.com/>  
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## For further information write to:

Hitachi Semiconductor  
 (America) Inc.  
 179 East Tasman Drive,  
 San Jose, CA 95134  
 Tel: <1> (408) 433-1990  
 Fax: <1> (408) 433-0223

Hitachi Europe GmbH  
 Electronic components Group  
 Dornacher Straße 3  
 D-85622 Feldkirchen, Munich  
 Germany  
 Tel: <49> (89) 9 9180-0  
 Fax: <49> (89) 9 29 30 00  
 Hitachi Europe Ltd.  
 Electronic Components Group.  
 Whitebrook Park  
 Lower Cookham Road  
 Maidenhead  
 Berkshire SL6 8YA, United Kingdom  
 Tel: <44> (1628) 585000  
 Fax: <44> (1628) 778322

Hitachi Asia Pte. Ltd.  
 16 Collyer Quay #20-00  
 Hitachi Tower  
 Singapore 049318  
 Tel: 535-2100  
 Fax: 535-1533

Hitachi Asia Ltd.  
 Taipei Branch Office  
 3F, Hung Kuo Building, No.167,  
 Tun-Hwa North Road, Taipei (105)  
 Tel: <886> (2) 2718-3666  
 Fax: <886> (2) 2718-8180

Hitachi Asia (Hong Kong) Ltd.  
 Group III (Electronic Components)  
 7/F., North Tower, World Finance Centre,  
 Harbour City, Canton Road, Tsim Sha Tsui,  
 Kowloon, Hong Kong  
 Tel: <852> (2) 735 9218  
 Fax: <852> (2) 730 0281  
 Telex: 40815 HITEC HX

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**Revision Record**

<b>Rev. Date</b>	<b>Contents of Modification</b>	<b>Drawn by</b>	<b>Approved by</b>
0.0 May. 19, 1999	Initial issue	M. Kawamura	M. Mishima
1.0 Nov. 8, 1999	Deletion of Preliminary	M. Kawamura	Y. Kasama
2.0 Dec. 6, 1999	DC Characteristics $I_{CC10}$ (L-version) max: 2/2 mA to 2.5/2.5 mA	M. Kawamura	Y. Kasama
3.0 Feb. 2, 2000	Change of datasheet title: HM5112805F Series, HM5113805F Series to HM5112805F-6, HM5113805F-6		

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